Optimization of Gamma Knife Radiosurgery

Michael Ferris
University of Wisconsin, Computer Sciences

David Shepard
University of Maryland School of Medicine

Supported by Microsoft, NSF and AFOSR

Overview

- Details of machine and problem
- Formulation
 - modeling dose
 - shot/target optimization
- Results
 - Two-dimensional data
 - Real patient (three-dimensional) data

The Gamma Knife



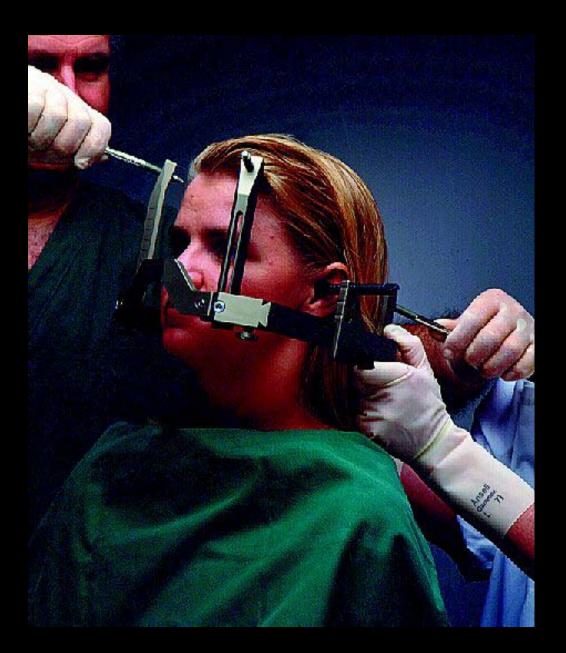
What disorders can the Gamma Knife treat?

- Malignant tumors from elsewhere in the body
- Malignant brain tumors
- Benign tumors within the head
- Vascular malformations
- Functional disorders of the brain
 - Parkinson's disease



201 cobalt gamma ray beam sources are arrayed in a hemisphere and aimed through a collimator to a common focal point.

The patient's head is positioned within the Gamma Knife so that the tumor is in the focal point of the gamma rays.

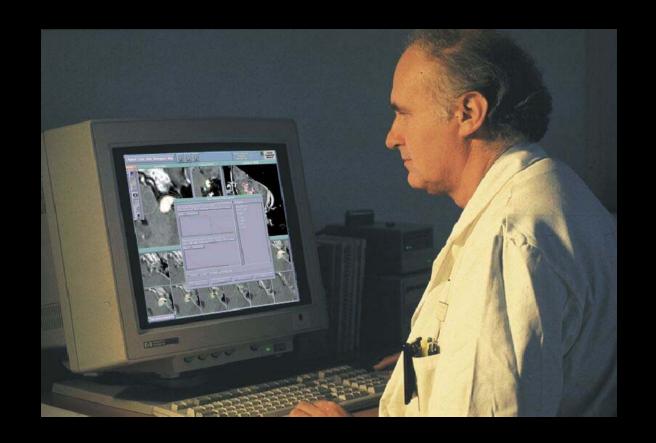


How is Gamma Knife Surgery performed?

Step 1: A stereotactic head frame is attached to the head with local anesthesia.



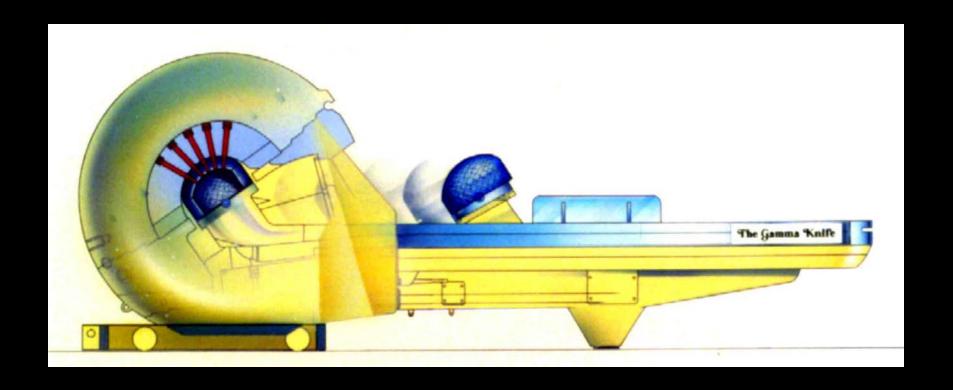
Step 2: The head is imaged using a MRI or CT scanner while the patient wears the stereotactic frame.



Step 3: A treatment plan is developed using the images. Key point: very accurate delivery possible.



Step 4: The patient lies on the treatment table of the Gamma Knife while the frame is affixed to the appropriate collimator.



Step 5: The door to the treatment unit opens. The patient is advanced into the shielded treatment vault. The area where all of the beams intersect is treated with a high dose of radiation.

Gamma Knife Statistics

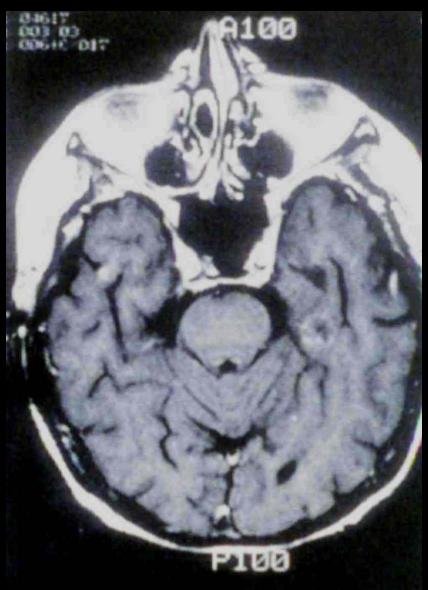
- 120 Gamma Knife units worldwide
- Over 20,000 patients treated annually
- Accuracy of surgery without the cuts
- Same-day treatment

Expensive instrument

Before

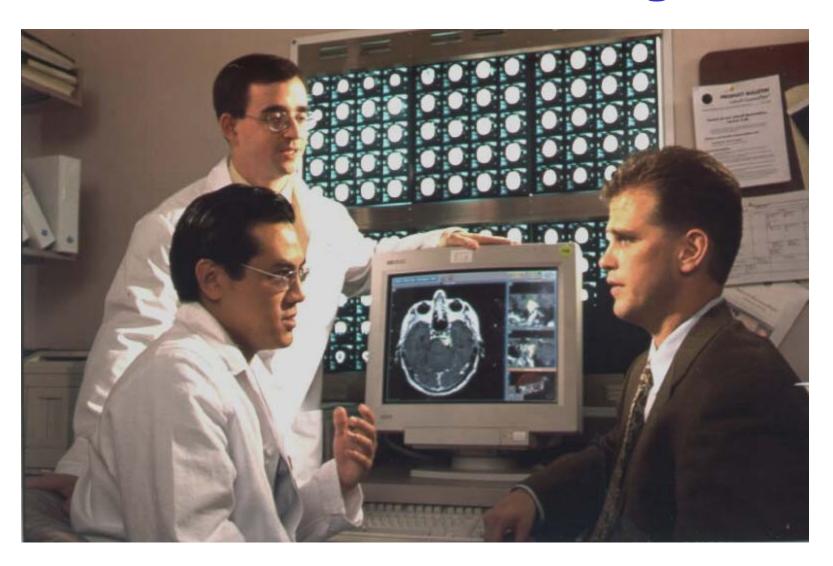
After







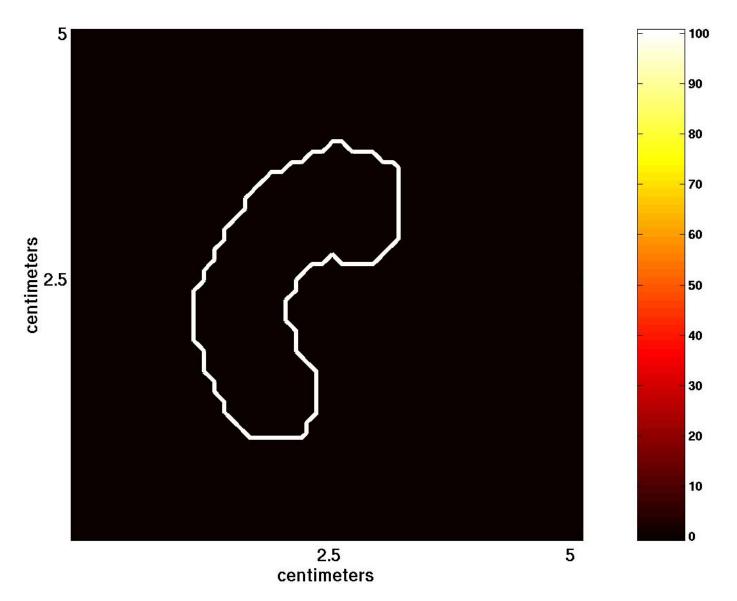
Treatment Planning



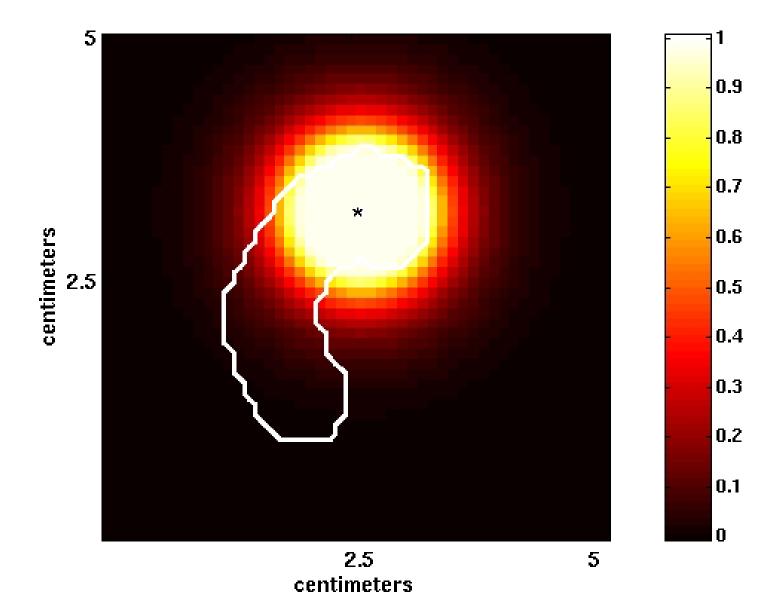
Treatment Planning

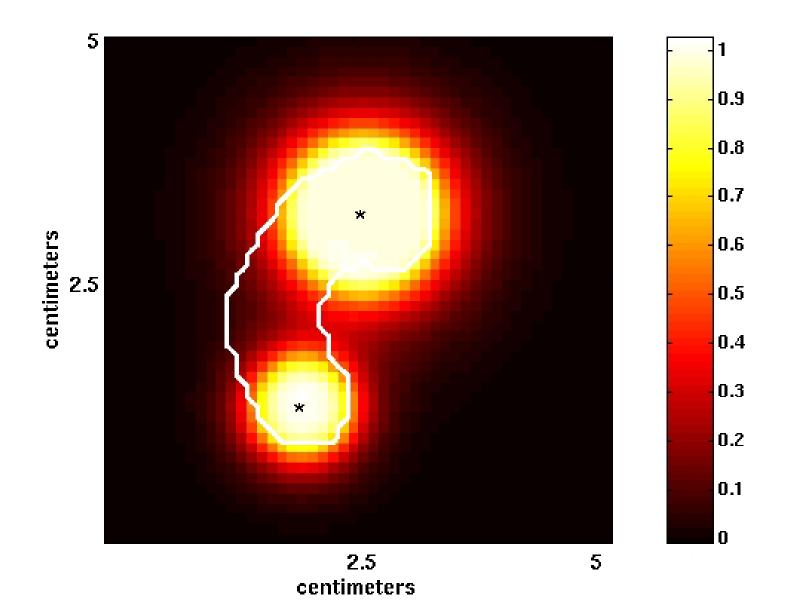
- Through an iterative approach we determine:
 - the number of shots
 - the shot sizes
 - the shot locations
 - the shot weights
- The quality of the plan is dependent upon the patience and experience of the user

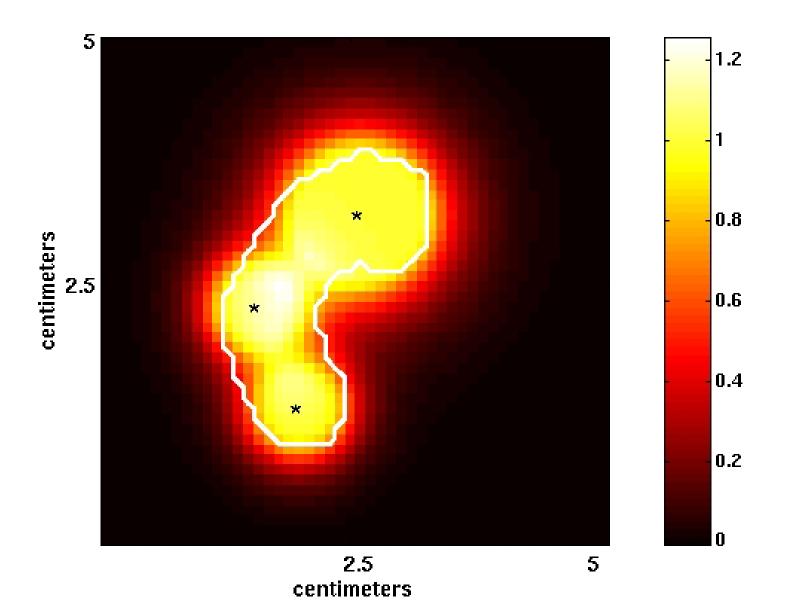
Target

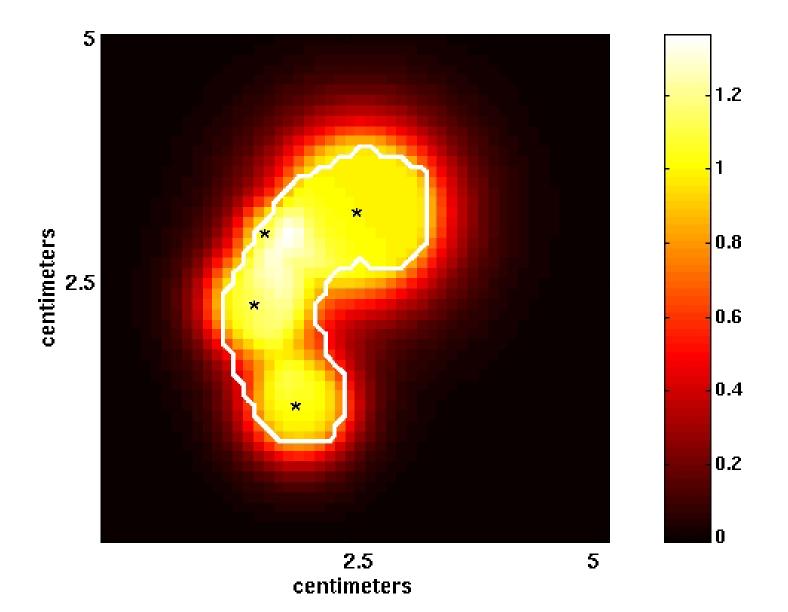


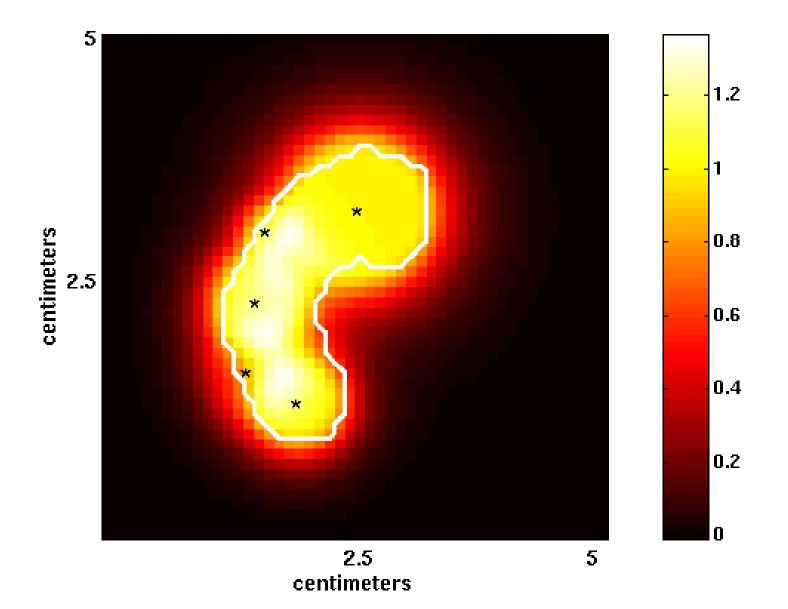
1 Shot











Automated Planning

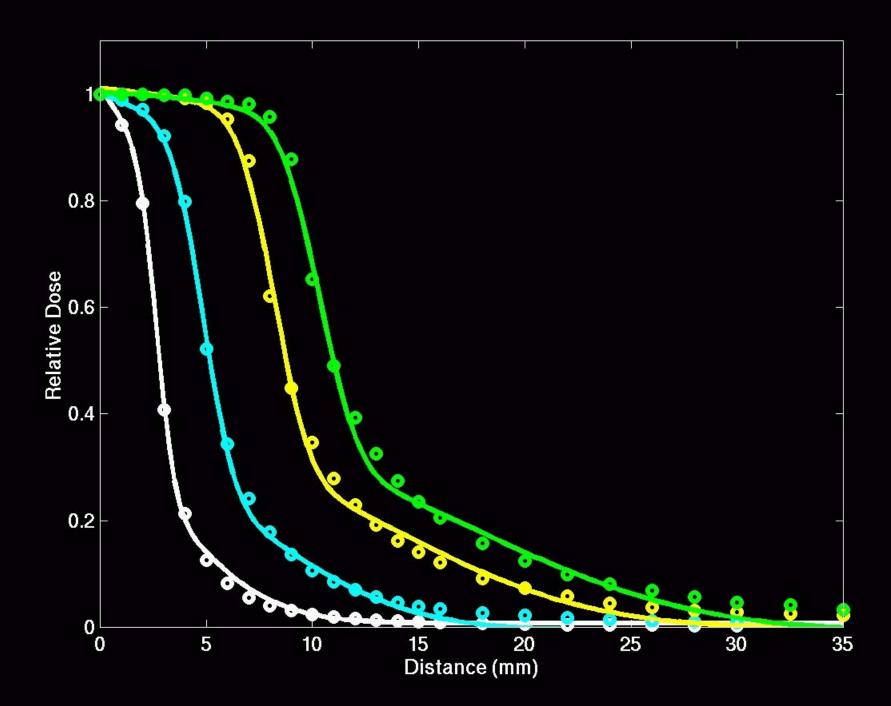
- Develop a fully automated approach to Gamma Knife treatment planning
- Better tumor dose coverage
- Reduced dose to normal tissue
- More efficient treatments
- Reduced time commitment for neurosurgeon

Computational Model

- Target volume (from MRI or CT)
- Maximum number of shots to use
 - Which size shots to use
 - Where to place shots
 - How long to deliver the shot
 - Conform to Target (50% isodose curve)
 - Real-time optimization

Ideal Optimization

$$\begin{aligned} & \min_{t_{s,w},x_{s},y_{s}} & Dose(NonTarget) \\ & subject \ to & Dose(i,j) = \sum_{s \in S,w \in W} t_{s,w} D_{w}(x_{s},y_{s},i,j) \\ & 0.5 \leq Dose(Target) \leq 1 \\ & t_{s,w} \geq 0 \\ & |S| \leq N \end{aligned}$$



Dose calculation

- Measure dose at distance from shot center in 3 different axes
- Fit a nonlinear curve to these measurements (nonlinear least squares)
- Functional form from literature, 10 parameters to fit via least-squares

$$m_1 \, erf(\frac{d_1(x) - r_1}{\sigma_1}) + m_2 \, erf(\frac{d_2(x) - r_2}{\sigma_2})$$

Environment

- All data fitting and optimization models formulated in GAMS
 - Ease of formulation / update
 - Different types of model
- Nonlinear programs solved with CONOPT (generalized reduced gradient)
- LP's and MIP's solved with CPLEX

Nonlinear Approach

Let x_s, y_s be variable locations s = 1, 2, ..., N $D_w(x_s, y_s, i, j)$ is nasty nonlinear function

$$What width shot to use at x_s, y_s?$$

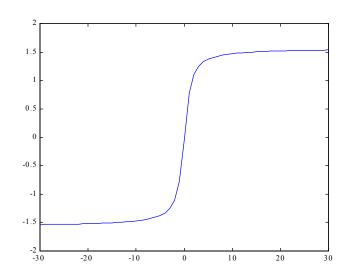
$$\psi_{s,w} = \begin{cases} 1 & \text{if shot s is width w} \\ 0 & \text{else} \end{cases}$$

$$\underline{T}\psi_{s,w} \leq t_{s,w} \leq \overline{T}\psi_{s,w}$$

$$\sum_{w} \psi_{s,w} \leq 1$$

Iterative Approach

· Approximate via "arctan"



$$\forall s \in S$$

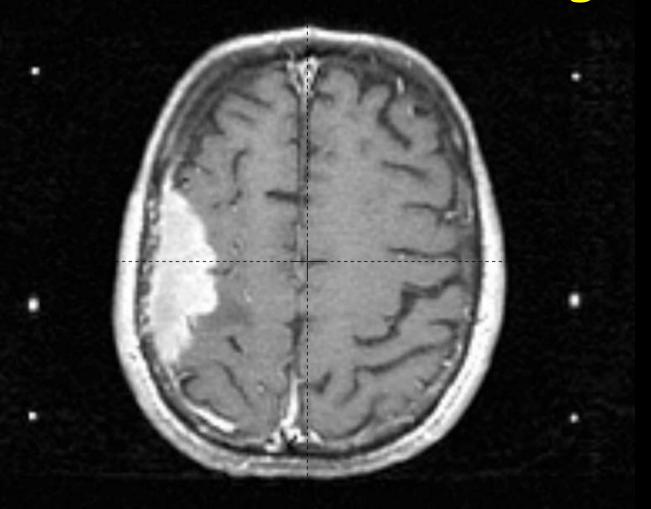
$$\sum_{w} arctan(t_{s,w}) \leq \frac{\pi}{2}$$

• First, solve with coarse approximation, then refine and reoptimize

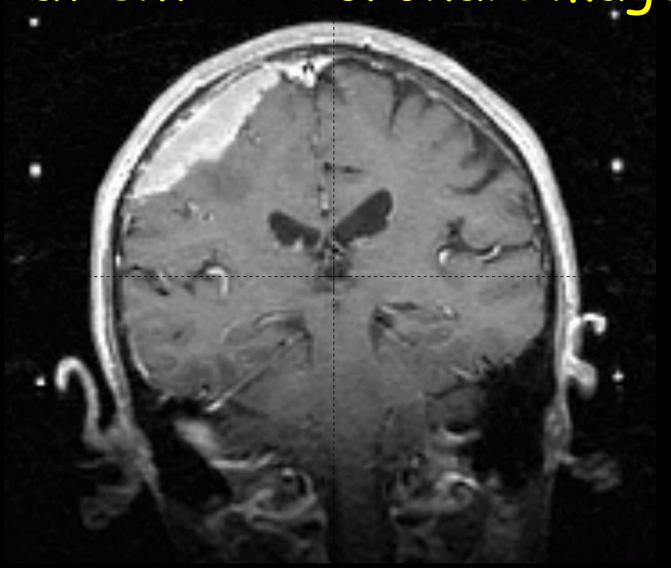
Continuation Approach

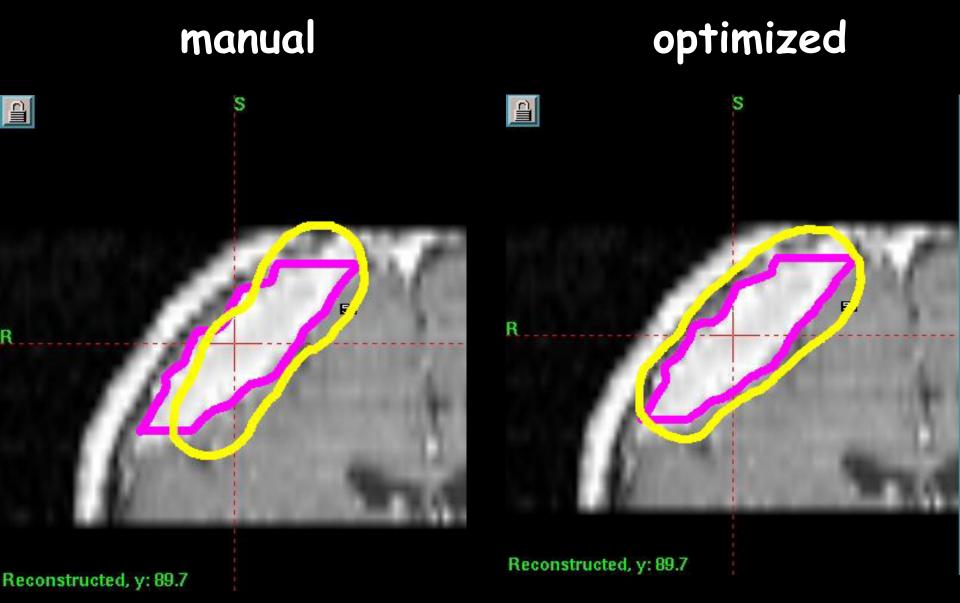
- Rotate data (prone/supine)
- Conformity subproblem (P)
- Coarse grid shot optimization
- Refine grid (add violated locations)
- Refine smoothing parameter
- Round and solve MIP for exposure times

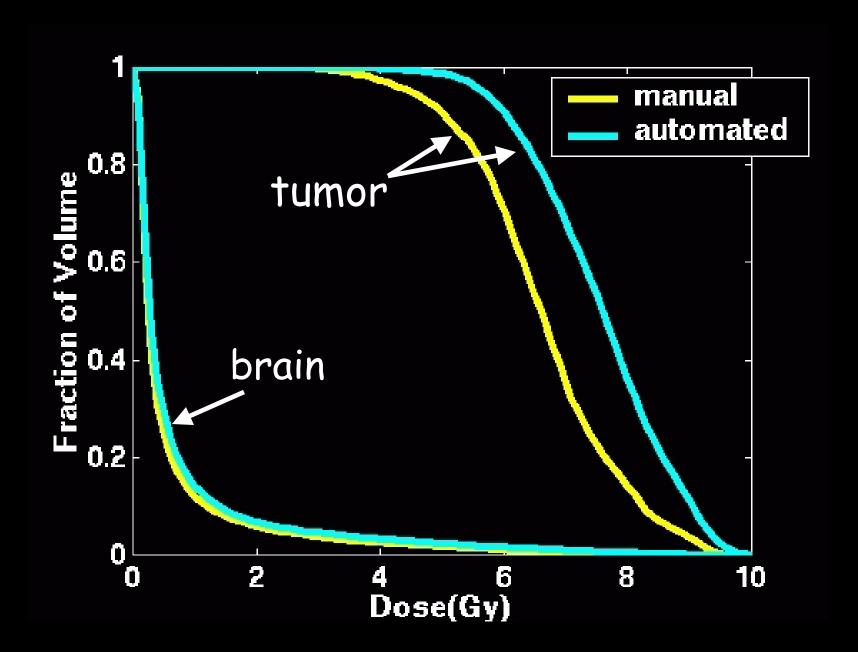
Patient 1 - Axial Image



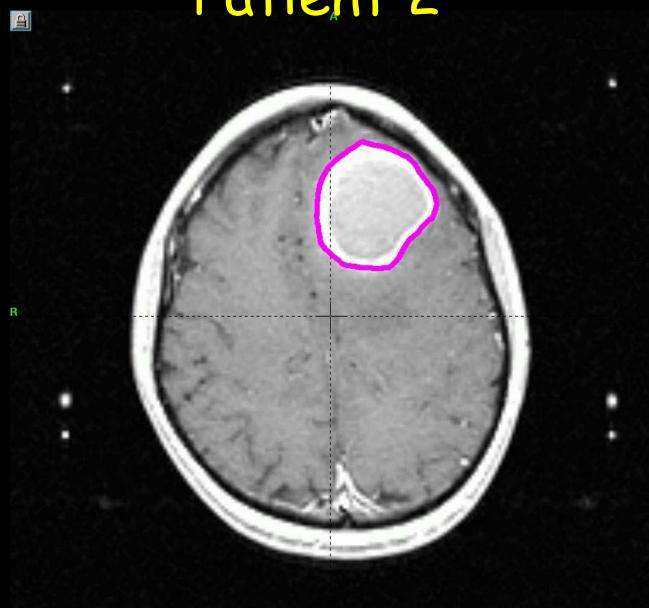
Patient 1 - Coronal Image





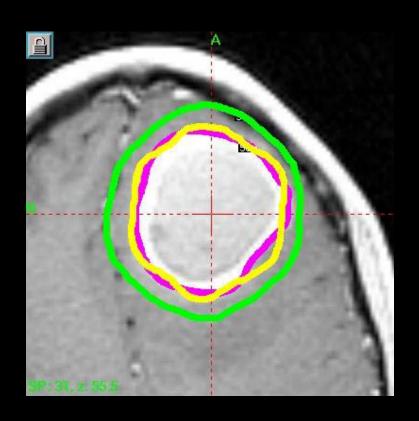


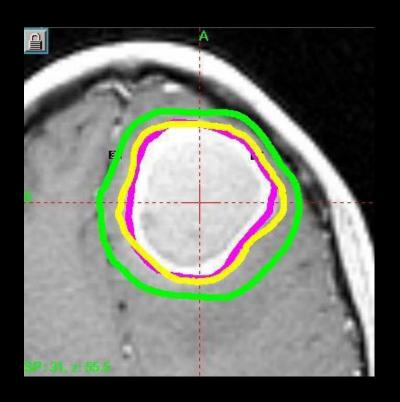
Patient 2



Patient 2 - Axial slice

15 shot manual 12 shot optimized

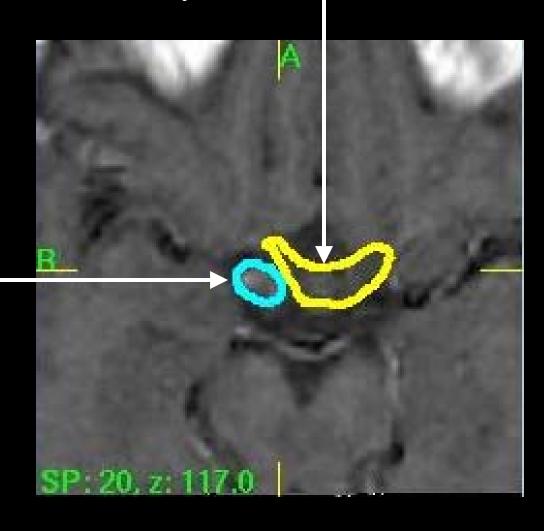


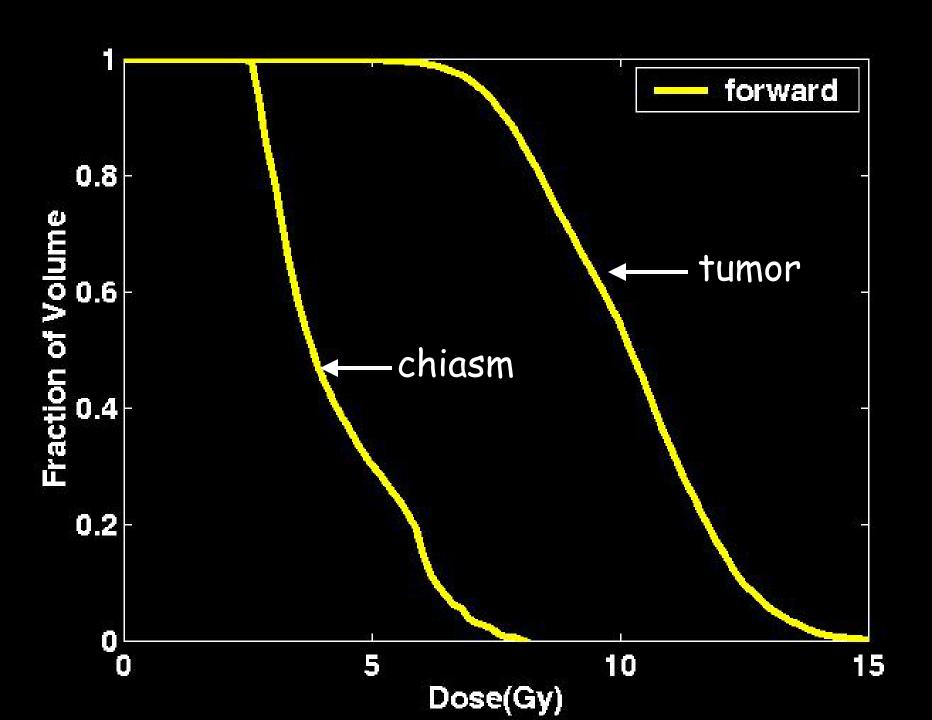


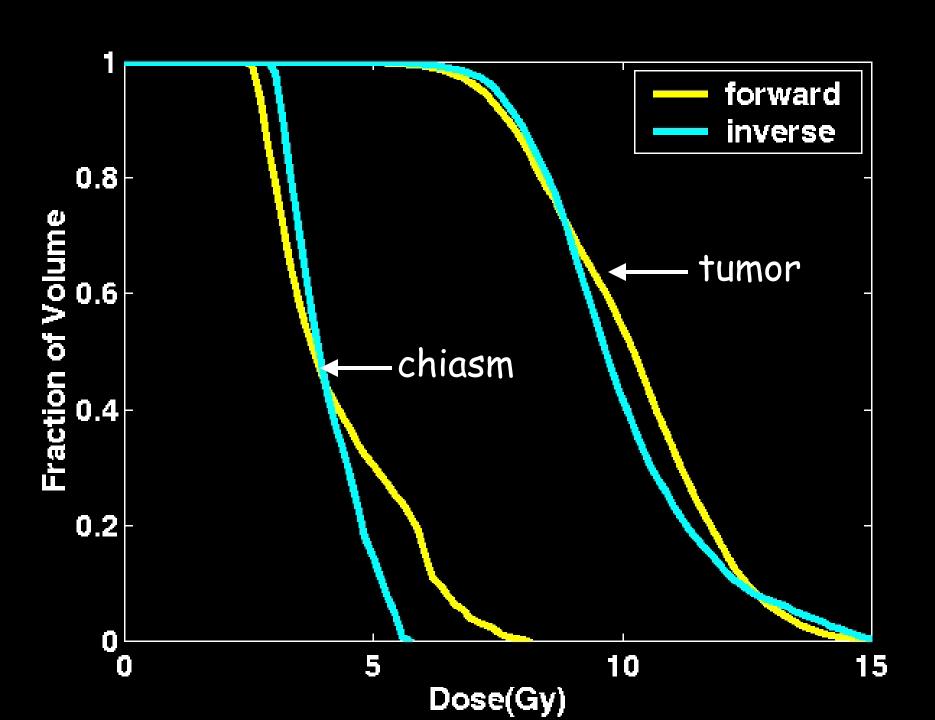
Patient 3

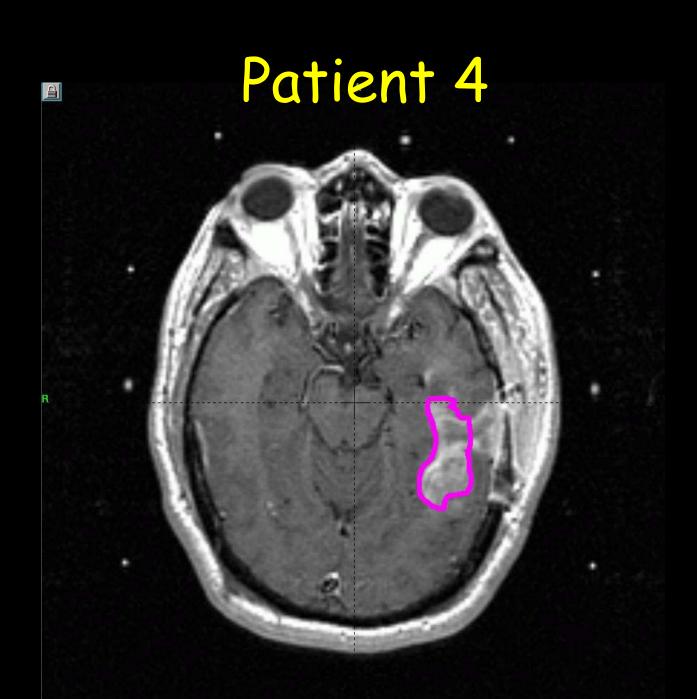
optic chiasm

pituitary _adenoma





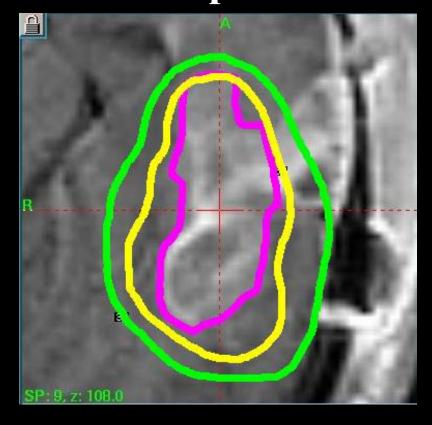




Patient 4 - Axial slice

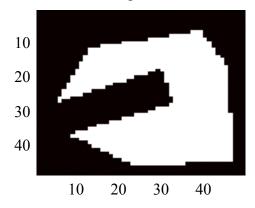
7 shot manual

7 shot optimized

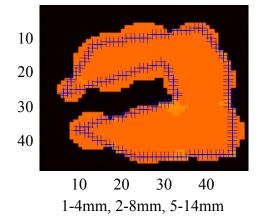


Skeletons (J.-H. Lim)

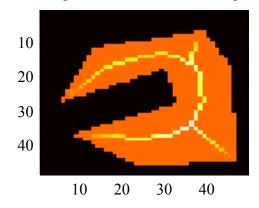
a. Target area



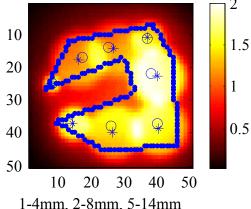
c. 8 initial shots are identified



b. A single line skeleton of an image



d. An optimal solution: 8 shots



1-4mm, 2-8mm, 5-14mm

Starting Point Comparison

Average Run Time	Size of Tumor		
	Small	Medium	Large
Random	2 min 33 sec	17 min 20 sec	373 min 2 sec
(Std. Dev)	(40 sec)	(3 min 48 sec)	(90 min 8 sec)
SLSD	1 min 2 sec	15 min 57 sec	23 min 54 sec
(Std. Dev)	(17 sec)	(3 min 12 sec)	(4 min 54 sec)

Status

- Automated plans have been generated retrospectively for over 30 patients
- The automated planning system is now in use at U. Maryland Hospital
- Head to head against the neurosurgeon

Robustness

- High-quality conformal dose distributions are obtained independent of starting point
- Optimization performs well for targets over a wide range of sizes and shapes

Conclusions

- An automated treatment planning system for Gamma Knife radiosurgery has been developed using optimization techniques (GAMS, CONOPT and CPLEX)
- The system simultaneously optimizes the shot sizes, locations, and weights
- Automated treatment planning should improve the quality and efficiency of radiosurgery treatments