

Global Optimization with GAMS

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Agenda

- Global Optimization Introduction
- GAMS Global Solvers
- Performance & Quality
- Linking a new Code



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Algebraic Modeling Languages

- High-level programming languages for large scale mathematical optimization problems
- Algebraic formulation
 - § Syntax similar to mathematical notation
 - § Does not contain any hints how to process it
- Do not solve optimization problems directly but call appropriate external algorithms (solvers)



Goals

- Support of decision making process
- Efficient handling of mathematical optimization problems
- Simplify model building and solution process
- Increase productivity and support maintainable models



Global Optimization (GO)

 Practical optimization problems are often nonlinear and non-convex

 They may contain disconnected feasible regions with multiple local optima

 The aim of Global Optimization is to find the best solution of all local optima



Examples for GO Applications

- Chemotherapy and radiotherapy design
- Chemical data and process analysis
- Differential equations
- Engineering design
- Environmental engineering
- Financial model development
- Laser design
- Packing and loading configuration design
- Staff scheduling
- Vehicle routing and scheduling

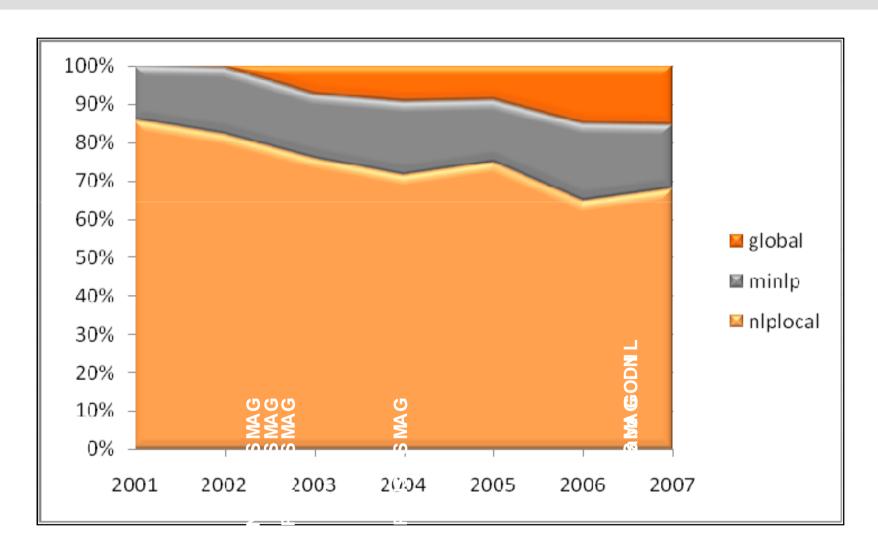


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Relevance of GO





GAMS Global Solvers

BARON Branch-and-Reduce Optimization

Navigator for proven global solutions

by The Optimization Firm, USA

• LGO Lipschitz Global Optimizer by Pintér

Consulting Services, Canada

OQNLP OptQuest/NLP Multi-start Solver by

OptTek Systems/Optimal Methods, USA

• LINDOGlobal MINLP solver for proven global

solutions by LINDO Systems, USA

The solvers differ in the methods they use, in whether they find globally optimal solution with proven optimality, in the size of models they can handle, and in the characteristics of models they accept.



Optimization Methods

BARON

- Branch-and-bound algorithms
- Range reduction techniques
- Under-estimators for objective and constraints

• LGO

- Branch-and-bound based global search
- Stochastic sampling procedure

OQNLP

 Starts NLP solvers from a set of starting points chosen by the Scatter Search software OptQuest

LINDOGlobal

- Branch-and-cut methods
- Breaks an NLP into a list of sub problems



Model Requirements

BARON

- LP and NLP solver for sub problems
- Knowledge about model algebra

• LGO

- Only Lipschitz-continuity of objective function
- Black box models (external equations)

OQNLP

- Requirements of local solver used during search
- Smooth problems

LINDOGlobal

- Local solver for nonlinear sub problems
- Instruction list interface



Solution Quality Metrics

• LGO

- Estimated statistical or Lipschitz lower bound
- Stochastic convergence to global optimum

OQNLP

 Scatter Search ensures stochastic convergence towards the global optimum

BARON & LINDOGlobal

- Deterministic lower bound
- Relative/absolute gap similar to MIP
 è Proven global optimum



BARON vs. LINDOGlobal

Both find proven global optimum

BARON

- Requires finite bounds for all variables and nonlinear expressions to guarantee global optimum
- Can return the k best solutions
- Not tied to one sub solver

LINDOGlobal

- Copes with trigonometric functions
- Handles non-smooth functions directly



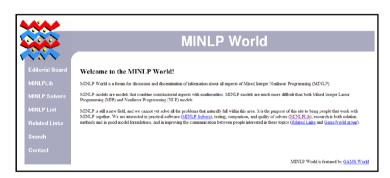
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MINLP Library

- Collection of Mixed Integer Nonlinear Programming models (~250 models)
- Large and varied set of both theoretical and practical models
- Helps algorithm developers to test their source

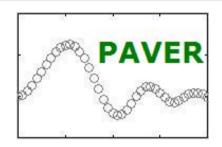


www.gamsworld.org/minlp/minlplib.htm



PAVER

 Performance Analysis and Visualization for Effortless Reproducibility

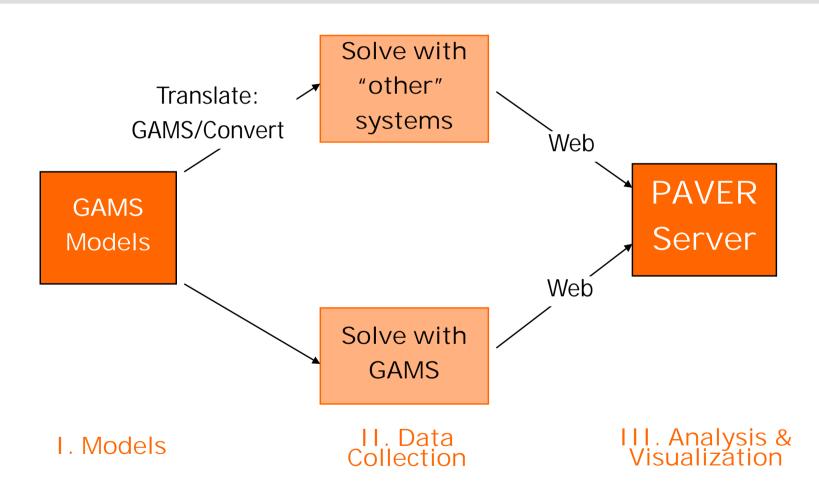


- Online server to facilitate performance testing and analysis/visualization
- Results sent via e-mail in HTML format
 - System independent

www.gamsworld.org/performance/paver

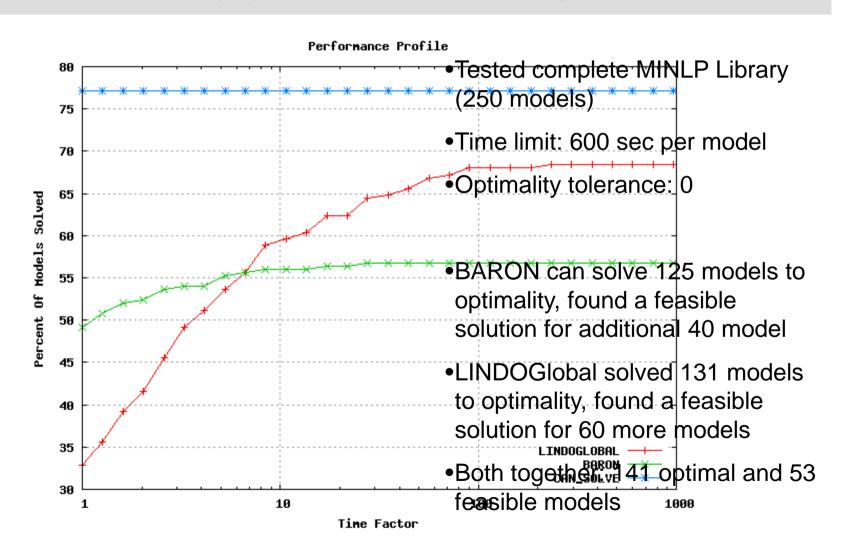


Open Testing Architecture





PAVER: LINDOGlobal vs. BARON





Benchmarking pitfalls

- Solvers may contain bugs really!
 - Wrong solution returned
 - Wrong objective returned
 - False claims of feasibility/optimality
- Solvers will use different termination checks/tolerances
 - Difficult to compare "quality" of solutions
 - Common standard of comparison is lacking
- PAVER does not check validity of input data



GAMS/Examiner

- Purpose: to make an unbiased, independent report on the merit of points
- Points may come from GAMS or a solver
 - GAMS passes the previous solution as initial iterate
 - Solvers pass solutions back to GAMS
- Useful during solver debugging helps pinpoint problems
 - Most checks are obvious
- Does checks on the scaled and unscaled (original) model
- All solution tolerances can be adjusted, default is tight
- Different points can be checked
- Examiner only *reports*, it doesn't *fix*



GAMS/Bench

- Tool to help facilitate benchmarking of GAMS solvers
- Compares resource usage of solvers selected by the user
- Creates problem matrix once and spawns it to all solvers
- Can create trace files used by PAVER
- Can call GAMS/Examiner for every tested solver
- Comes free with every GAMS system (depends on licensed solvers)



GAMS/Bench Output

Primal constraints satisfied (tol = 1e-006)

```
alan, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.158, 0, 8, 9, 4, 24, 3, NA, 1, 1, 2.92500000000001, 2.925, 0.078, 167, 0, 1, #
 batch, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.158, 0, 74, 47, 24, 191, 22, NA, 1, 1, 285506.510639964, 285506.510639948, 22.828, 128068, 0, 26, #
 batchdes, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.158, 0, 20, 20, 9, 53, 10, NA, 1, 1, 167427.6571147, 167427.6571147, 0.234, 1180, 0, 4, #
 beuster,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.158,0,115,158,52,398,159,NA,8,3,128002.432361333,13002.3195417608,601,2904299,0,378,#
 contvar, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.165, 0, 285, 297, 87, 1281, 530, NA, 8, 3, 813303.696565387, 392084.341377606, 602.187, 675054, 0, 3, #
 csched1,MinlP,LinDoGLoBaL,CoNoPT,CPLEX,39231.172,0,23,77,63,174,8,Na,1,1,-30639.2578450033,-30639.2578557346,26.922,114747,0,145,#
 deb10, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.173, 0, 130, 183, 11, 692, 432, Na, 1, 1, 209. 427811754669, 209. 427811754669, 154.375, 26218665, 0, 1, #
 dosemin2d,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.175,0,119,166,32,4379,4080,NA,14,6,NA,NA,NA,NA,NA,NA,
Sau-opt5, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.175, 0, 10, 21, 12, 47, 20, NA, 1, 1, 8.0736575822132, 8.0736575822132, 61.296, 5046, 0, 1, #
\neg du-opt, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.175, 0, 10, 21, 13, 47, 20, NA, 1, 1, 3.55634005788148, 3.55634005788148, 110.656, 9075, 0, 1, #
Fleg all s,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.177,0,28,8,7,220,196,NA,13,3,NA,NA,601.032,0,0,0,#
Heg disc s, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.184, 0, 28, 8, 4, 220, 196, NA, 13, 3, NA, NA, 601.031, 0, 0, 0, #
 eg disc2 s,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.19,0,28,8,3,220,196,NA,13,3,NA,NA,603.313,0,0,0,#
 eg int s,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.197,0,28,8,3,220,196,NA,13,3,NA,NA,601.875,0,0,0,#
 elf,MinlP,LindogLoBal,ConopT,CpLEX,39231.204,0,39,55,24,178,30,NA,1,1,0.191666664686662,0.191666665776661,49.422,172820,0,54,#
 eniplac,MinLP,LinDoGLoBaL,CoNoPT,CPLEX,39231.205,0,190,142,24,511,48,Na,8,3,-131806.374611992,-168871.02357847,601,6313823,0,7,#
 enpro48,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.212,0,215,154,92,742,29,NA,1,1,187277.259422014,187277.259422014,52.938,244931,0,1,#
 enpro56,MinlP,LindoGloBal,CoNoPT,CPLEX,39231.213,0,192,128,73,651,24,Na,8,3,322067.383696514,263140.351531923,601,3810986,0,74,#
 ex1221,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.22,0,6,6,3,17,2,NA,1,1,7.66718006881327,7.66718006881313,0.031,38,0,1,#
 x1222,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.22,0,4,4,1,9,2,NA,1,1,1.07654308333225,1.07654308333225,0.016,34,0,1,#
 x1223,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.22,0,14,12,4,40,17,NA,1,1,4.5795824024366,4.57958240243657,0.578,1953,0,2,#
 x1223a,Minlp,LindogLoBal,Conopt,Cplex,39231.22,0,10,8,4,32,9,Na,1,1,4.57958240243672,4.5795824024367,0.031,157,0,2,#
 x1223b,Minlp,LindogLoBaL,Conopt,CpLEX,39231.22,0,10,8,4,32,17,Na,1,1,4.57958240243672,4.57958240237498,0.125,711,0,2,#
 ex1224, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.22, 0, 8, 12, 8, 31, 6, NA, 1, 1, -0.943470500 622735, -0.943470500522735, 0.359, 3410, 0, 3, #
 ex1225, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.22, 0, 11, 9, 6, 27, 2, NA, 1, 1, 31, 31, 0.141, 279, 0, 1, #
 ex1226, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.22, 0, 6, 6, 3, 15, 2, NA, 1, 1, -17, -17, 0.031, 91, 0, 2, #
 |x1233,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.22,0,65,53,12,221,28,NA,1,1,155010.671278216,155010.671278216,61.297,255059,0,100,#
 |x1243,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.22,0,97,69,16,329,36,NA,1,1,83402.50|64102569,83402.506410257,32.891,131465,0,9,#
 x1244,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.221,0,130,96,23,469,52,NA,1,1,82042.9052197479,82042.9052197471,301.61,710319,0,88,#
 x1252, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.224, 0, 44, 40, 15, 118, 36, NA, 1, 1, 128893.741013226, 128893.741010754, 17.813, 194740, 0, 325, #
 x1252a,MinlP,LindoGloBal,ConoPT,CPLEX,39231.224,0,35,25,9,94,36,Na,1,1,128893.741013318,128893.741013318,117.5,531460,0,676,#
 x1263, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.226, 0, 56, 93, 72, 241, 32, NA, 1, 1, 19.6, 19.6, 19.6, 31.422, 321060, 0, 110, #
 x1263a,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.226,0,36,25,24,153,32,NA,1,1,19.6,19.6,6.938,76749,0,1,#
 x1264, MINLP, LINDOGLOBAL, CONOPT, CPLEX, 39231.226, 0, 56, 89, 68, 237, 32, Na, 1, 1, 8.6000000000000, 8.6, 93.375, 292976, 0, 31, #
 x1264a,MINLP,LINDOGLOBAL,CONOPT,CPLEX,39231.227,0,36,25,24,153,32,NA,1,1,8.60000000000002,8.6,1,4035,0,1,#
```



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Linking a new Code



Solver Links

- Standardized Solver Interface
 - Return Codes, Limits, Interrupts, ...
 - Common attributes (e.g. time) through GAMS options
 - Specific options through option file
 - à allows "hassle free" replacement of solvers: option minlp=lindoglobal;

- Open architecture assures seamless communication
 - IO Library (C, Fortran, Delphi) provides access to Matrix, Function/Derivative Evaluator, ...



MISQP* Link

```
// EVALUATION OF PROBLEM FUNCTIONS
with mymodel
                                                     // EVALUATION OF GRADIENTS
do begin
                                                     with mymodel
                                                                                                                 // OPTIMIZATION BLOCK : CALL MISQP IN REVERSE COMMUNICATION
  for i := 1 to m
                                                     do begin
                                                                                                                repeat
   do begin
                                                       for i := 1 to m
                                                                                                                  if (IFAIL = 0) or (IFAIL = -1)
      if nlfstart^[i] <> 0
                                                        do begin
                                                                                                                  then
                                                           if nlfstart^[i] <> 0
                                                                                                                     FUNC (F, G, X);
         neweval(nlfstart^[i],nlfend^[i],codefun^,p
                                                              neweval(nlstart^[i],nlend^[i],code^,pool^,XVal^,
                                                                                                                  if (IFAIL = 0) or (IFAIL = -2)
        equnonlinear := 0.0;
                                                           jac := equfirst^[i];
      equlinear := 0.0;
                                                           while jac <> nil
                                                                                                                     GRAD (DF, DG, X);
      jac := equfirst^[i];
                                                           do begin
      while jac <> nil
                                                              if jac^.NL
                                                                                                                  MISQP (ENum,
      do begin
                                                              then
                                                                                                                        ME,
        if not jac'.NL and ((objreform = 0) or (ja
                                                                curgrad := evalgrad[jac^.col]
                                                                                                                        MMAX,
                                                                                                                        VNum,
            equlinear := equlinear + X[VInd[jac^.co
                                                                 curgrad := jac^.coef;
                                                                                                                        NINT,
        iac := iac^.nextrow;
                                                              if ((equtype[i] = 2) and (direction = 0)) or ((e
                                                                                                                        NBIN,
        end:
                                                                                                                        NMAX,
      if (objreform = 1) and (i = objrow)
                                                                curgrad := -curgrad;
                                                                                                                         MNN,
                                                              if (objreform = 1) and (i = objrow)
                                                                                                                        X[O],
        begin
                                                              then
                                                                                                                        F,
         if direction = 0
                                                                 begin
                                                                                                                        G[0],
                                                                 if jac'.col <> objvar
                                                                                                                        DF[O],
           F := (equlinear + equnonlinear - rhs[i]
                                                                 then
                                                                                                                        DG[O],
         else
                                                                   DF[VInd[jac^.col]] := curgrad / (-objcoef)
                                                                                                                         υ[<mark>0</mark>],
            F := -(equlinear + equnonlinear - rhs[i
                                                                                                                        XL[O],
         end:
                                                              else
                                                                                                                        XU[O],
      if (objreform = 0) or (i <> objrow)
                                                                 begin
                                                                                                                        B[O],
                                                                 if (objreform = 0) or (jac^.col <> objvar)
                                                                                                                         OpACC,
         G[EInd[i]] := equlinear + equnonlinear - r
                                                                                                                        OnACCOP.
      if ((equtype[i] = 2) and (direction = 0)) or
                                                                   DG[dg2(EInd[i],VInd[jac^.col])] := curgrad
                                                                                                                         OpMAXIT,
                                                                 end;
                                                                                                                        OpMAXPEN,
        G[EInd[i]] := -G[EInd[i]];
                                                              jac := jac^.nextrow;
                                                                                                                        Onmaxund.
      end;
                                                              end:
                                                                                                                        OpRESOPT,
   if objreform=0
                                                           if objreform = 0
                                                                                                                        OpNONMON,
                                                                                                                        OnMAXNDE.
     begin
                                                              begin
                                                                                                                        OpIPRINT,
      if direction = 0
                                                              if direction = 0
                                                                                                                        OpMODE,
                                                                                                                        OpIOUT,
        F:= X[VInd[objvar]]
                                                                DF[VInd[objvar]] := objcoef
                                                                                                                        IFAIL,
      else
                                                                                                                        RW[O],
        F:= -X[VInd[objvar]];
                                                                DF[VInd[objvar]] := -objcoef;
                                                                                                                        LRW,
      end;
                                                              end:
                                                                                                                         IW[O],
   end;
                                                           end;
                                                                                                                        LIW,
end:
                                                        end;
                                                                                                                        LW[O],
                                                     end:
                                                                                                                        LLW);
                                                                                                                until IFAIL >= 0;
```



BARON Input

```
MODULE: NLP;
VARIABLES x2, x3, x4, x5, x6;
EQUATIONS e2,e3,e4;
e2: x3^2 + x4^3 + x2 == 6.24264068711929;
e3: -x4^2 + x3 + x5 == 0.82842712474619;
e4: x2*x6 == 2;
OBJ: minimize (-1 + x2)^2 + (x2 - x3)^2 + (x3 - x4)^3
               + (x4 - x5)^4 + (x5 - x6)^4;
STARTING_POINT{
x2: -1;
x3: 2;
x4: 1;
x5: -2;
x6: -2;
```



LINDOGlobal Input

```
BEGINMODEL
              TEST
VARIABLES
 x2
       -1E30
                  -1
                         1E30
                               C
 x3 -1E30
                         1E30 C
 x4 -1E30
                         1E30 C
 x5 -1E30
                  -2
                         1E30
                  -2
 xб
      -1E30
                         1E30
OBJECTIVES
 OBJ
               MINIMIZE
   EP_PUSH_NUM
               -1
   EP PUSH VAR
               x2
   EP_PLUS
   EP_SQR
   EP_PUSH_VAR x2
               x3
   EP_PUSH_VAR
   EP MINUS
   EP_SQR
   EP PLUS
   EP_PUSH_VAR x3
```



Contacting GAMS

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