

# GAMS' Extended Mathematical Programming Framework

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### Agenda

- General Algebraic Modeling System
- New Solution Concepts
- Extended Mathematical Programming



### **Agenda**

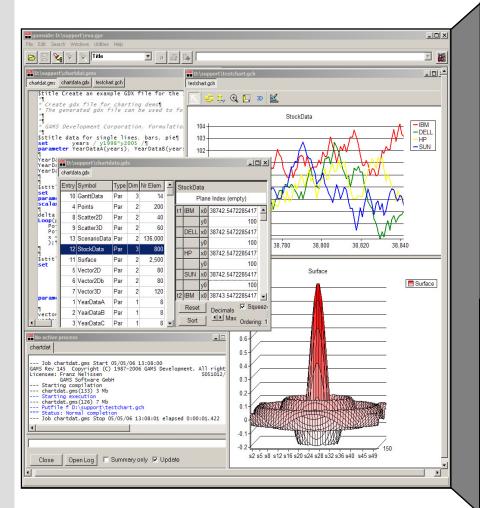
General Algebraic Modeling System

**New Solution Concepts** 

Extended Mathematical Programming



#### **GAMS** at a Glance



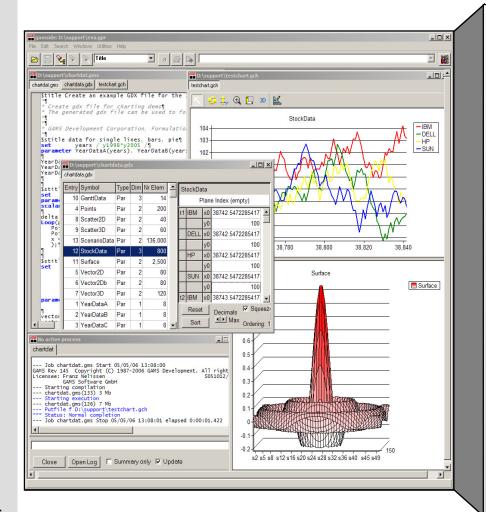
#### General Algebraic Modeling System

- Roots: World Bank, 1976
- Went commercial in 1987
- GAMS Development Corp.
- GAMS Software GmbH
- Broad academic & commercial user community and network





#### **GAMS** at a Glance



#### General Algebraic Modeling System

- Algebraic Modeling Language
- 25+ Integrated Solvers
- 10+ Supported MP classes
- 10+ Supported Platforms
- Connectivity- & Productivity Tools
  - IDE
  - Model Libraries
  - GDX, Interfaces & Tools
  - Grid Computing
  - Benchmarking
  - Compression & Encryption
  - Deployment System
  - •



### Agenda

General Algebraic Modeling System

**New Solution Concepts** 

Extended Mathematical Programming



#### Traditional but fundamental concept of AMLs

#### Different layers with separation of

- model and data
- model and solution methods
- model and operating system
- model and interface





#### **Current state: Model-Side**

Traditional problem format

$$\min_{x} c(x)$$
 s.t.  $A_1(x) \le b_1$ ,  $A_2(x) = b_2$ 

- Support for complementarity constraints
- Interactions between models possible
  - Series of models
  - Scenario analyses / parallelized model runs
  - Iterative sequential feedback
  - Decomposition



#### **Current state: Solver-Side**

Support of a wide collection of established MP classes through solver cluster!

# → Tremendous algorithmic and computational progress

#### LP

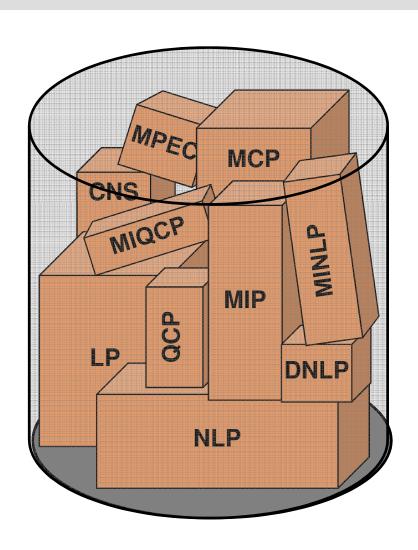
in fact only restricted by available memory

#### **MIP**

- Some (academic) problems still unsolvable
- Commercial problems mostly docile

#### **NLP/MINLP**

 Predictions are problem and data specific, global vs. local solutions





### Non-traditional solution concepts

- MP with Equilibrium Constraints (MPEC)
  - > NLPEC
    - Solves MPECs through reformulation into NLPs
- Solving non-integer models as MCPs
  - > PATHNLP
    - reformulation via KKT conditions (1<sup>st</sup> and 2<sup>nd</sup> order deriv.)
- Mathematical Programming System for General Equilibrium analysis
  - > MPSGE
- Indicator Constraints (CPLEX)
  - Alternative to conventional BigM formulations



### Non-traditional solution concepts

- Global Optimization
  - > BARON, LINDOGLOBAL
    - Proven global optimum
  - > LGO, OQNLP
    - Stochastic convergence to global optimum
- Stochastic Programming
  - > DECIS
  - solves two-stage stochastic linear programs with recourse
  - two-stage decomposition (Benders)
  - stores only one instance of the problem and generates scenario subproblems as needed
  - solution Strategies (Universe problem/Importance sampling)

• ...



### **New solution concepts**

- Extended Nonlinear Programs
- Embedded Complementarity Systems
- Bilevel Programs
- Disjunctive Programs
- - Breakouts of traditional MP classes
  - No conventional syntax
  - Limited support with common model representation
  - Incomplete/experimental solution approaches
  - Lack of reliable/any software



#### What now?

#### Do not:

- overload existing GAMS notation right away!
- attempt to build new solvers right away!

#### But:

- Use existing language features to specify additional model features
- Distribute information as part of the production system
- Express extended model in symbolic form and apply existing matured solution technology
  - → Extended Mathematical Programming (EMP)



### Agenda

General Algebraic Modeling System

**New Solution Concepts** 

**E**xtended **M**athematical **P**rogramming



#### **GAMS "Solver" EMP**

- Translation services
- Uses existing language features to specify additional model features
- Expresses extended model in symbolic form and passes it to existing solution methods via embedded GAMS calls
- Reads solution back into original space
- Facilitates to write out the reformulated model



### **Extended Nonlinear Programming**

#### Soft penalization of constraints

• Model:  $\min_{x_1,x_2,x_3} \exp(x_1)$ s.t.  $\log(x_1) = 1$  $x_2^2 \le 2$  $x_1/x_2 = \log(x_3), 3x_1 + x_2 \le 5, x_1 \ge 0, x_2 \ge 0$ 

Additional information:

```
$onecho > %emp.info%
Adjustequ
e1 sqr 5
e2 MaxZ 2
$offecho
```

```
$onecho > %gams.scrdir%empinfo2.scr
Strategy MCP
Adjustequ
e1 sqr 5
e2 MaxZ 2
$offecho
```

EMP Tool creates the NLP model (or the MCP via KKT) :

$$\min_{\substack{x_1, x_2, x_3 \\ \text{s.t.}}} \exp(x_1) + 5 \|\log(x_1) - 1\|^2 + 2 \max(x_2^2 - 2, 0)$$
s.t. 
$$x_1/x_2 = \log(x_3), 3x_1 + x_2 \le 5, x_1 \ge 0, x_2 \ge 0$$



### **Embedded Complementarity Systems**

Models with side constraints/variables:

$$\min_{x} f(x,y)$$
s.t.  $g(x,y) \le 0 \quad (\pm \lambda \ge 0)$ 

$$H(x,y,\lambda) = 0 \quad (\pm y \text{ free})$$

Additional Information:

EMP Tool creates the MCP model

$$\nabla_{x}\mathcal{L}(x, y, \lambda)$$
  $\perp x$  free  $-\nabla_{\lambda}\mathcal{L}(x, y, \lambda)$   $\perp \lambda \geq 0$   $H(x, y, \lambda) = 0$   $\perp y$  free



### **ECS Example**

Rutherford, Thomas F. (http://www.mpsge.org/nlptarget/)

```
parameter
                          Terminal capital stock
        kterm
UTIL..
                    UTILITY = E = SUM(t, 10 * dfactor(t) * L(t) * LOG(C(t)/L(t)));
CC(t)..
                       C(t) = E = Y(t) - I(t);
YY(t)..
                       Y(t) = E = phi * L(t) **(1-kvs) * K(t) **kvs;
                       K(t) = L = (1-delta) **10 * K(t-1) + 10 * I(t-1) + kinit tfirst(t);
KK(t)..
TERMCAP..
                       kterm = E = sum(tlast, (1-delta) **10 * K(tlast) + 10 * I(tlast));
model ramsey NLP Model using parameter kterm /all/;
set iter /iter1*iter20/;
kterm = kinit * power(1+q, card(t));
parameter
                 invest(t,iter) Investment in successive iterations
                 kt(iter)
                                  Terminal capital stock in successive iterations;
loop(iter,
        kt(iter) = kterm;
        solve ramsey maximizing UTILITY using NLP;
        invest(t, iter) = I.L(t);
        kterm = sum(tlast(t), K.L(tlast) * Y.L(t)/Y.L(t-1));
);
```



#### **EMP Formulation**

```
*Substitute TERMCAP of NLP by TERMCAPV (using variable KTERMV instead of parameter kterm)

TERMCAPV.. KTERMV =E= sum(tlast, (1-delta)**10 * K(tlast) + 10 * I(tlast));

*First-order-condition for terminal capital stock variable

SSTERM.. sum(tlast(t),I(t)/I(t-1) - Y(t)/Y(t-1)) =E= 0;

model ramseynlpd /UTIL,CC,YY,KK,TERMCAPV,SSTERM/;

$onecho > %emp.info%
dualequ SSTERM KTERMV
$offecho

option nlp=emp;

solve ramseynlpd maximizing UTILITY using nlp;
```



#### **Hierarchical Models**

Bilevel Program:

$$\min_{x,y} f(x,y)$$
s.t.  $g(x,y) \le 0$ ,
 $y \text{ solves } \min_{s} v(x,s) \text{ s.t. } h(x,s) \le 0$ 

Additional Information:

\$onecho > %emp.info% Bilevel x min v h \$offecho

 EMP Tool automatically creates an MPEC by expressing the lower level optimization problem through its optimality conditions



#### **Bilevel Model**

Conejo A J, Castillo E, Minguez R, and Garcia-Bertrand R; Decomposition Techniques in Mathematical Programming, Springer, Berlin, 2006.



### **EMP Information File + EMP Summary Log**

```
option nlp=emp;
$onecho > %emp.info%
bilevel x1 x2 x3 x4
min h1 defh1 e1
min h2 defh2 e2
$offecho
solve bilevel us nlp min z;
```



### **Disjunction Example**

Raman & Grossmann, Comp. & Chem. Eng., 18, 7, p.563-578, 1994.

- Three jobs (A,B,C) must be executed sequentially in three steps, but not all jobs require all the stages. Once a job has started it cannot be interrupted.
- The objective is to obtain the sequence of task, which minimizes the completion time.

Stage Job	1	2	3
Α	5	1	3
В	-	3	2
С	2	4	-



#### **Data Definition**

```
table p(j,s) processing time
   1 2 3
A 5 3
B 3 2
C 2 4
alias (j,jj),(s,ss);
parameter c(j,s) stage completion time
         w(j,jj) maximum pair wise waiting time
         pt(j) total processing time;
set less(j,jj) upper triangle;
c(j,s) = sum(ss$(ord(ss)<=ord(s)), p(j,ss));
w(j,jj) = \mathbf{smax}(s, c(j,s) - c(jj,s-1));
pt(j) = sum(s, p(j,s));
less(j,jj) = ord(j) < ord(jj);
```



### **Basic Model Definition**

#### **Above equation is incomplete!**

If (j,jj) is active then (jj,j) should be relaxed



### **Traditional BigM Formulation**

```
binary variable y(j,jj) job precedence;
parameter big the famous big M;
big = sum(j, pt(j));
biq=100000;
seq(j,jj) $ (not sameas(j,jj))..
x(j) + w(j,jj) = l = x(jj) + big*( <math>y(j,jj) $less(j,jj)
                                 + (1-v(jj,j))$less(jj,j));
model m / all /; m.optcr=0;
solve m using MIP minimizing t;
```



#### **CPLEX Indicator Formulation**

```
seq(j,jj) \{(not sameas(j,jj))... x(j) + w(j,jj) = 1 = x(jj);
binary variable v(j,jj) job precedence;
equation
           dummy force names into model;
dummy.. sum(less(j,jj), y(j,jj)) = g= 0;
model m / all /:
file copt / cplex.opt /; put copt '* inicators for example 1';
loop (less(j,jj),
   put / 'indic ' seq.tn(j,jj) '$' y.tn(j,jj) yes
       / 'indic ' seq.tn(jj,j) '$' y.tn(j,jj) NO );
putclose; m.optfile=1;
                                    * inicators for example 1
                                    indic seq('A','B') $y('A','B')
                                                                      YES
                                    indic seq('B','A')$y('A','B')
                                                                       NO
solve m using MIP minimizing t;
                                    indic seq('A','C') $y('A','C')
                                                                      YES
                                    indic seq('C','A')$y('A','C')
                                                                       NO
                                    indic seq('B','C') $y('B','C')
                                                                      YES
                                    indic seq('C','B') $y('B','C')
                                                                       NO
```



### **EMP Disjunction Formulation**

```
seq(j,jj) (not sameas(j,jj))... x(j) + w(j,jj) = l = x(jj);
model m / all /;
file emp / '%emp.info%' /; put emp '* EMP for example 1';
loop (less(j, jj),
  put / 'disjunction * ' seq.tn(j,jj) ' else ' seq.tn(jj,j) );
putclose:
option mip=emp;
solve m using MIP minimizing t;
                * EMP for example 1
                disjunction * seq('A','B') else seq('B','A')
                disjunction * seq('A','C') else seq('C','A')
```



### **EMP Info Syntax Summary**

```
AdjustEQU equ abs|sqr|maxz|huber|... {
    weight { param } }
DualEqu {equ var}
DualVar {var equ}
BiLevel {var} { MAX|MIN obj {equ} }
Disjunction [NOT] var|* {equ} { ELSEIF [NOT] var|* {equ} }
```



#### Conclusion

#### EMP is

- a framework for automated symbolic reformulations
- non-exhaustive and experimental
- free

#### EMP needs

- Input from other researchers !!
  - Automate further reformulation strategies
    - More of the same, boring to some, exiting to others
    - Concurrent strategies
  - Examples from existing publications
    - EMP Library



#### Conclusion

#### EMP promotes non-traditional MP classes

- Automates symbolic reformulations to avoid error-prone and time-consuming manual algebra (re)writing
- Offers solutions through established and powerful solution engines
- makes theoretical benefits available to users from a wide variety
- provides nonstandard model information to solver developers → new algorithms/software?

EMP bridges the gap between academia and industry!



## Thank you!

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